

Adversarially Robust One-class Novelty Detection

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Recall: One-class Novelty Detection

- One-class novelty detection model is trained with examples of **a particular class** and is asked to identify whether a query example belongs to the same known class.
- Example:
	- **Known class** (normal data): 8
	- **Novel classes** (anomalous data): 0-7 & 9 (the rest of classes)

Recall: One-class Novelty Detection

- Most recent advances are based on the **autoencoder** architecture.
- Given an autoencoder that learns the distribution of the known class, we expect that the **normal data** are reconstructed accurately while the **anomalous data** are not.

Attacking One-class Novelty Detection

- How to generate adversarial examples against a novelty detector?
- If a test example is **normal**, **maximize** the reconstruction error.
- If a test example is **anomalous**, **minimize** the reconstruction error.

Goal: Adversarially Robust Novelty Detection

- Novelty detectors are **vulnerable** to adversarial attacks.
- Adversarially robust method specifically designed for novelty detectors is needed.
- A **new** research problem.

Observation: Generalizability

- Unique property: Preference for **poor** generalization of reconstruction ability.
- However, autoencoders have **good** generalizability.

Observation: Feature Denoising

• Adversarial perturbations can be removed in the **feature** domain.

[Xie et al. CVPR'19]

Our Solution

• **Observations**: Generalizability and Feature Denoising.

• **Assumption**: One can **largely** manipulate the latent space of a novelty detector to remove adversaries to a great extent, and this would not hurt the model capacity but **helps** if in a proper way.

• **Solution**: Learning **principal latent space**.

PCA Rephrased

• *h()* computes the **mean vector** and the first *k* **principal components** of the given data collection *X*:

 $h(\mathbf{X}, k) : \mathbf{X} \to \{\boldsymbol{\mu}, \mathbf{U}\}\$

• *f()* performs the forward PCA:

$$
f(\mathbf{X}; \boldsymbol{\mu}, \tilde{\mathbf{U}}) = (\mathbf{X} - \boldsymbol{\mu} \mathbf{1}^{\top}) \tilde{\mathbf{U}}
$$

$$
\mathbf{X}_{pca} = f(\mathbf{X}; \boldsymbol{\mu}, \tilde{\mathbf{U}})
$$

• *g()* performs the inverse PCA:

 $g(\mathbf{X}_{pca}; \boldsymbol{\mu}, \tilde{\mathbf{U}}) = \mathbf{X}_{pca} \tilde{\mathbf{U}}^{\top} + \boldsymbol{\mu} \mathbf{1}^{\top}$ $\hat{\mathbf{X}} = g(f(\mathbf{X}; \boldsymbol{\mu}, \tilde{\mathbf{U}}); \boldsymbol{\mu}, \tilde{\mathbf{U}})$

- **Vector-PCA** performs PCA on the **vector** dimension.
- **Spatial-PCA** performs PCA on the **spatial** dimension.

v

h

• Step 1: **Forward Vector-PCA**, i.e., *fv()*

$$
\mathbf{Z}_{adv} \in \mathbb{R}^{s \times v} \longrightarrow \mathbf{Z}_V \in \mathbb{R}^{s \times 1}
$$

Latent space Vector-PCA space

• Step 2: **Forward Spatial-PCA**, i.e., *fs()*

 $Z_V \in \mathbb{R}^{S \times 1} \longrightarrow Z_S \in \mathbb{R}^{k_S \times 1}$

Vector-PCA space Spatial-PCA space

$$
\{\boldsymbol{\mu}_S, \tilde{\mathbf{U}}_S\} = h_S(\mathbf{Z}_V^{\top}, k_S)
$$

$$
\mathbf{Z}_S^{\top} = f_S(\mathbf{Z}_V^{\top}; \boldsymbol{\mu}_S, \tilde{\mathbf{U}}_S)
$$

- Step 3: **Inverse Spatial-PCA**, i.e., *gs()*
- Step 4: **Inverse Vector-PCA**, i.e., *gv()*

$$
\mathbf{Z}_S \in \mathbb{R}^{k_S \times 1} \longrightarrow \mathbf{Z}_{pls} \in \mathbb{R}^{s \times v}
$$

Spatial-PCA space **Principal latent space**

$$
\hat{\mathbf{Z}}_V^{\top} = g_S(\mathbf{Z}_S^{\top}; \boldsymbol{\mu}_S, \tilde{\mathbf{U}}_S)
$$

$$
\mathbf{Z}_{plr} = g_V(\hat{\mathbf{Z}}_V; \boldsymbol{\mu}_V, \tilde{\mathbf{U}}_V)
$$

Learning Principal Latent Components

• **Principal latent components**:

 $\{\mu_V, \tilde{U}_V, \mu_S, \tilde{U}_S\}$

• **Training time**: Train along with the network weights by exponential moving average (EMA). $\{\mu_V^t, \tilde{U}_V^t\} = \{\mu_V^{t-1}, \tilde{U}_V^{t-1}\} + \eta_V(h_V(\mathbf{Z}^t) - \{\mu_V^{t-1}, \tilde{U}_V^{t-1}\})$

 $\{\mu_S^t, \tilde{U}_S^t\} = \{\mu_S^{t-1}, \tilde{U}_S^{t-1}\} + \eta_S(h_S(\mathbf{Z}^t) - \{\mu_S^{t-1}, \tilde{U}_S^{t-1}\})$

• **Inference time**: Perform the cascade PCA process with the fixed and well-trained parameters:

 $\{\mu^*_V, \tilde{U}^*_V, \mu^*_S, \tilde{U}^*_S\}$

Defense Mechanism

- **Vector-PCA** replaces the perturbed latent vectors with the clean principal latent vector.
- **Spatial-PCA** removes the remaining perturbations on the Vector-PCA map.

Defense Mechanism

- Combine **adversarial training**.
- The proposed PrincipaLS process can robustify **any** AE-based novelty detectors.
	- AE, VAE, AAE, ALOCC (CVPR'18), GPND (NeurIPS'18), etc.

Results

- Evaluation metric: mean of AUROC
- PrincipaLS is effective on **5** datasets against **6** attacks for **7** novelty detection methods.

Analysis

• PrincipaLS reconstructs **every** input example to the known class (digit 2).

Analysis

- (a) No Defense under clean data (b) No Defense under PGD attack (c) PGD-AT under PGD attack (d) PrincipaLS under PGD attack
- PrincipaLS enlarges the reconstruction errors of anomalous data to a great extent.

